

Derivations of the conditions used in RBC1.m

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Consider a simple RBC model where output is produced with capital, labor of the form

$$\max_{c_t, k_{t+1}, N_t} \sum_t \beta^t \left(\frac{c_t^{1-\eta}}{1-\eta} - AN_t \right) \quad (1)$$

subject to

$$c_t + k_{t+1} = \zeta_t K_t^\rho N_t^{1-\rho} + (1-\delta)k_t \quad (2)$$

The FOC of the households are given by:

$$c_t^{-\eta} = \lambda_t$$

$$A = c_t^{-\eta} (1-\alpha) \zeta_t (K_t)^\rho N_t^{-\rho} = \frac{y_t}{c_t^\eta N_t} (1-\rho)$$

$$c_t^{-\eta} = \beta E_t c_{t+1}^{-\eta} \left\{ \rho \zeta_{t+1} K_{t+1}^{\rho-1} N_{t+1}^{1-\rho} + (1-\delta) \right\} = \beta E_t c_{t+1}^{-\eta} \left\{ \rho \frac{y_{t+1}}{K_{t+1}} + (1-\delta) \right\}$$

$$\zeta_t K_t^\rho N_t^{1-\rho} = y_t$$

The steady state of the model is:

$$Ac^\eta = (1-\rho)y/N$$

$$1 = \beta(\rho y/K + (1-\delta))$$

$$c + \delta K = y$$

$$y = \bar{\zeta} K^\rho N^{1-\rho}$$

Fix $\bar{R}, \rho, \delta, \eta, \bar{\zeta}$. The steady state values are

$$\beta = 1/\bar{R}$$

$$y/\bar{K} = [\frac{1}{\beta} - (1-\delta)]/\rho = (\bar{R} - 1 + \delta)/\rho$$

$$c/\bar{y} = 1 - \delta \bar{K}/\bar{y}$$

$$\bar{N}/\bar{y} = [1/\bar{\zeta} (y/\bar{K})^\rho]^{1/(1-\rho)}$$

$$i/\bar{K} = \delta$$

$$\bar{c} = (y/\bar{N} \frac{1-\rho}{A})^{1/\eta}$$

The log linearized first order conditions can be written as

$$0 = -\bar{i} i(t) - \bar{c} c(t) + \bar{y} y(t) \quad (3)$$

$$0 = \bar{i} i(t) - \bar{K} k(t) + (1 - \delta) \bar{K} k(t-1) \quad (4)$$

$$0 = \rho k(t-1) - y(t) + (1 - \rho) N(t) + \zeta(t) \quad (5)$$

$$0 = -\eta c(t) + y(t) - N(t) \quad (6)$$

$$0 = -\rho \bar{y} k(t-1) + \rho \bar{y} y(t) - \bar{K} \bar{R} r(t) \quad (7)$$

$$0 = E_t[-\eta c(t+1) + r(t+1) + \eta c(t)] \quad (8)$$

$$\zeta(t+1) = \psi \zeta(t) + \epsilon(t+1) \quad (9)$$

This is a system of 7 equations in 7 variables. The exogenous shock is ζ_t the state is k_t , the control variables are c_t, i_t, y_t, N_t, r_t . There are five static equation, one expectational equation and the law of motion of the technological disturbance.

The model in Uhlig's toolkit format is in rbc1.m